

University of Massachusetts Lowell
Department of Electrical and Computer Engineering

16.413 Linear Feedback

Problem set 5

1. Determine the root loci for the closed-loop unity negative feedback system $H(s) = 1$

$$G(s) = \frac{K}{s(s+1)(s^2+4s+5)}$$

2. Determine the root loci for the closed-loop unity negative feedback system $H(s) = 1$

$$G(s) = \frac{K(s+9)}{s(s^2+4s+11)}$$

- a. By adjustment of the gain K locate the closed-loop poles on the root loci such that the dominant closed-loop poles have a damping factor equal to 0.5.

3. Consider the closed-loop unity negative feedback system where

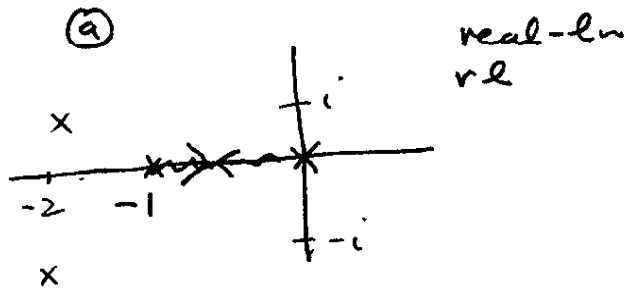
$$G(s) = \frac{1}{s^2(s+4)}$$

Design a compensator $H(s)$ such that the unit-step response of the system has an overshoot $\leq 25\%$ and a setting time of 5 seconds or less.

(5)

(1) $GH = \frac{k}{s(s+1)(s^2+4s+5)}$

poles: $s = \begin{cases} 0 \\ -1 \\ -2 \pm i \end{cases}$



(b) asympt.

$\sigma = \frac{0-1-2+i-2-i}{4-0} = \frac{-5}{4}$

$\phi = \frac{\pm(2n+1)\pi}{4-0} = \begin{cases} \pm\pi/4 \\ \pm3\pi/4 \end{cases}$



(c) jw-axis crossing

ch. eqn $GH+1 = 0$

$s^4 + 5s^3 + 9s^2 + 5s + k = 0$

s^4	1	9	k
s^3	5	5	
s^2	$\frac{45-5}{5}$	k	
s^1	$\frac{40-5k}{8}$		
s^0	k		

$\Rightarrow P(k) = 9s^2 + k = 0 \Rightarrow s^2 + 1 = 0$
 $s = \pm j$

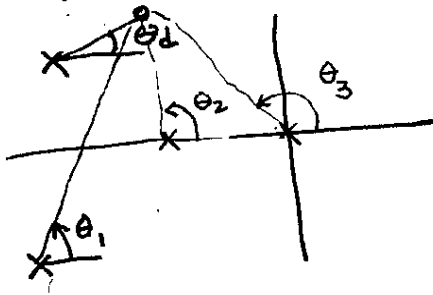
$\Rightarrow \frac{40-5k}{8} = 0 \Rightarrow k = 8$

(d) Breakaway pt
 $GH+1 = 0 \Rightarrow k = -\{s^4 + 5s^3 + 9s^2 + 5s\}$

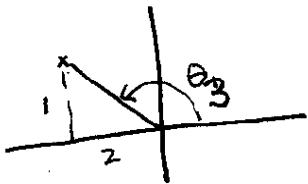
$\frac{dk}{ds} = 0 = 4s^3 + 15s^2 + 18s + 5 = 0 \Rightarrow s = -0.39$

$k = -\{s^4 + 5s^3 + 9s^2 + 5s\} \Big|_{s=-0.39} = 0.85$

(e) angle of departure



$$\pm (2n+1)\pi = -\theta_d - \theta_1 - \theta_2 - \theta_3$$



$$\theta_3 = \pi - \tan^{-1}\left(\frac{1}{2}\right)$$



$$\theta_2 = \pi - \tan^{-1}\left(\frac{1}{1}\right)$$



$$\theta_1 = \frac{\pi}{2}$$

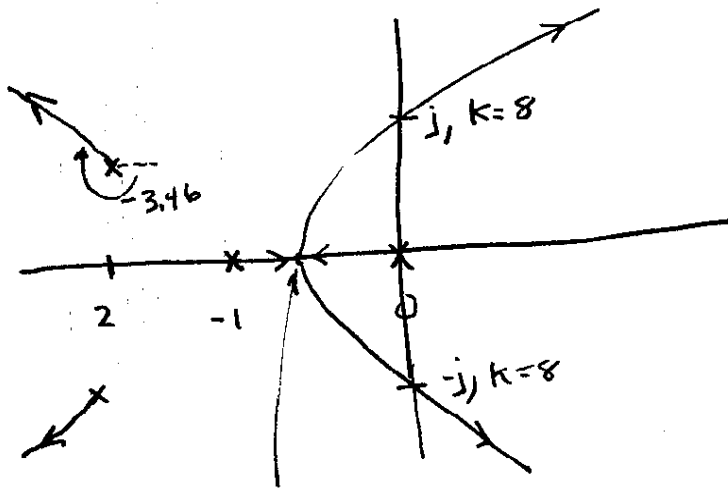
$$\pm (2n+1)\pi = -\theta_d$$

$$-\pi + \tan^{-1}\left(\frac{1}{2}\right)$$

$$-\pi + \tan^{-1}(1)$$

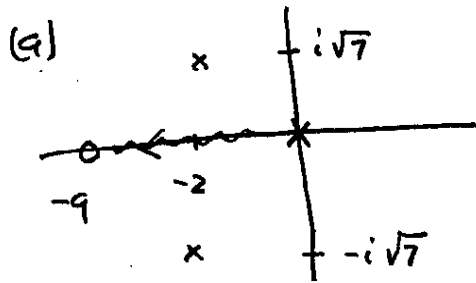
$$-\frac{\pi}{2}$$

$$\theta_d = -3.46$$



$$s = -0.39, k = 0.85$$

2



zeros: $s = -9$

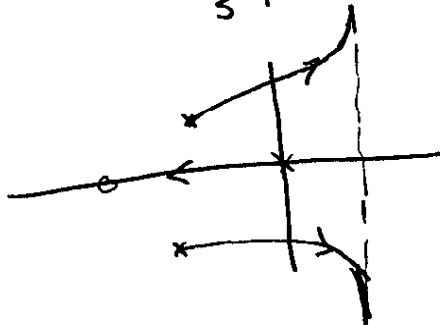
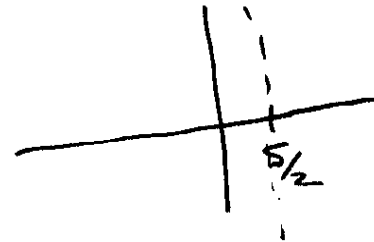
poles: $s = 0$

$s = -2 \pm i\sqrt{7}$

(b) asymptote

$$\sigma = \frac{+9 - 0 - 2 - i\sqrt{7} - 2 + i\sqrt{7}}{3 - 1} = \frac{5}{2}$$

$$\phi = \frac{\pm(2n+1)\pi}{3-1} = \frac{\pm\pi}{2}$$

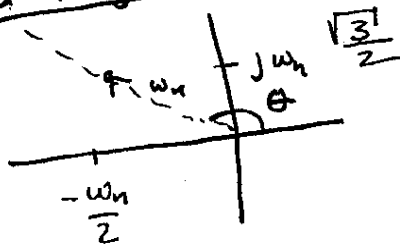


Note we have complex conjugate pair

given $\zeta = \frac{1}{2}$

$$s = -\frac{\omega_n}{2} \pm j\omega_n \sqrt{1 - \frac{1}{4}} = -\frac{\omega_n}{2} \pm j\omega_n \frac{\sqrt{3}}{2}$$

pole placement target

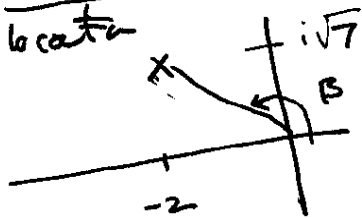


$$\theta = \pi - \tan^{-1}(\sqrt{3})$$

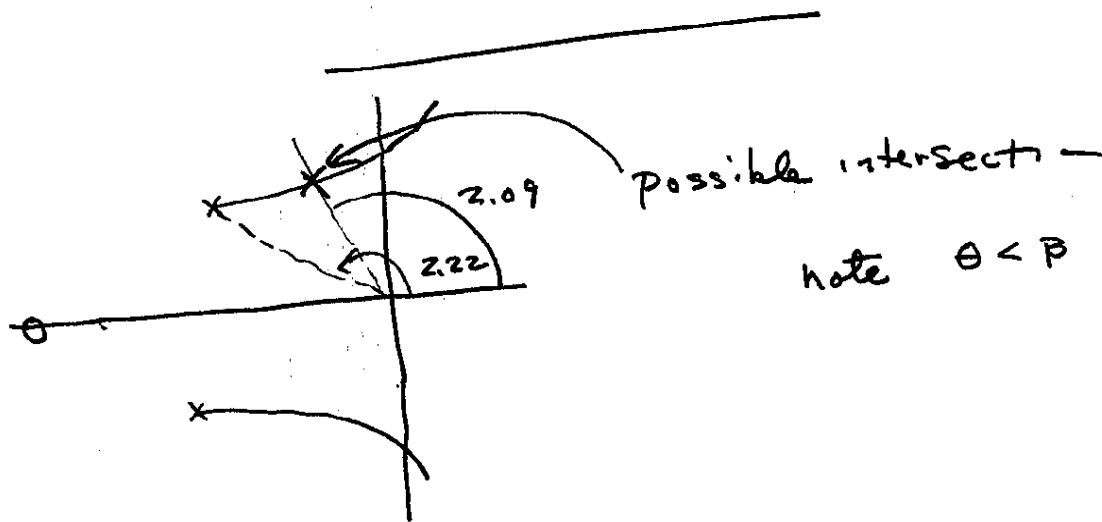
$$\theta = \pi - \frac{\pi}{3}$$

$$\boxed{\theta = \frac{2\pi}{3} = 2.09}$$

original pole location



$$\beta = \pi - \tan^{-1}\left(\frac{\sqrt{7}}{2}\right) = 2.218$$



note $\theta < \beta$ to intersect

$$s = \frac{\omega_n}{2}(-1 - j\sqrt{3})$$

Characteristic eqn

$$s^3 + 4s^2 + (k+11)s + 9k = 0$$

$$s = \frac{\omega_n}{2}(-1 - j\sqrt{3})$$

real part

$$(\omega_n - 18)k - 2\omega_n^3 + 4\omega_n^2 + 11\omega_n = 0$$

imag part

$$\frac{\sqrt{3}}{2}\omega_n [k - 4\omega_n + 11] = 0 \Rightarrow k - 4\omega_n + 11 = 0$$

$$\therefore k = 4\omega_n - 11$$

real part $k = 4\omega_n - 11$

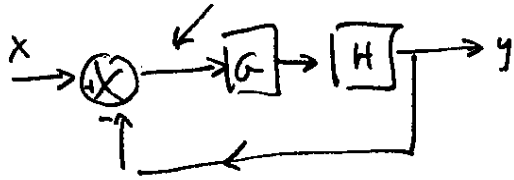
$$(\omega_n - 18)(4\omega_n - 11) - 2\omega_n^3 + 4\omega_n^2 + 11\omega_n = 0$$

$$\omega_n^3 - 4\omega_n^2 + 36\omega_n - 99 = 0$$

$$\omega_n = 3$$

$$k = 4 \cdot 3 - 11 = 1$$

3.



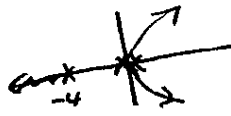
$$\frac{Y}{X} = \frac{GH}{1+GH}$$

$$Y = \frac{1}{s} \frac{GH}{1+GH}$$

$$y(\omega) = \int_0^{\infty} \frac{GH}{1+GH} = \int_0^{\infty} \frac{H \frac{1}{s^2(s+4)}}{1 + \frac{1}{s^2(s+4)} H} \Rightarrow 1 \text{ for } H = \begin{cases} k \\ ks \end{cases}$$

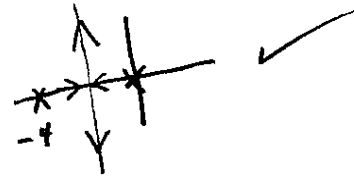
(a) $H = k$

$$GH = \frac{k}{s^2(s+4)}$$



(b) $H = ks$

$$GH = \frac{k}{s(s+4)}$$



$$\frac{Y}{X} = \frac{k}{s^2+4s+k}$$

$$\omega_n = \sqrt{k}$$

$$2\zeta\omega_n = 4 \Rightarrow \zeta = \frac{2}{\sqrt{k}}$$

$$M_p = e^{-\frac{\zeta\omega_n t}{\omega_n \sqrt{1-\zeta^2}}} \leq 0.25$$

$$e^{-\frac{\zeta\omega_n t}{\omega_n \sqrt{1-\zeta^2}}} \leq 0.25 \Rightarrow \frac{-2.9}{\sqrt{k-4}} \leq \ln(0.25)$$

$$t_s = \frac{-\ln(\epsilon)}{\zeta\omega_n}$$

$$\frac{-\ln(\epsilon)}{2} < 5$$

say $\epsilon = 0.02$

$$\frac{3.9}{2} < 5 \checkmark$$

\therefore satisfied @ 2%